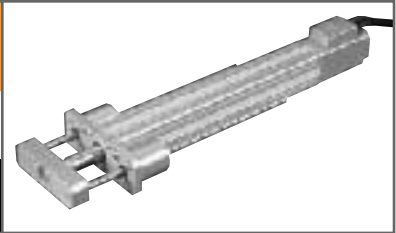


# RCS-RA55-100-GD

ROBO Cylinder Rod Type: Unit Width 55mm, 100W, Slim Shape w/ Double Guide



Type Rod (55mm wide) w/ double guides Stroke 50~300mm Load capacity 60kg (horizontal)/17.3kg (vertical)

Model specification items Series Type Encoder type Motor Guide type Speed type Stroke Cable length Options  
 (Example) RCS -RA55- A - 100 - GD - H - 300 - S - B

\* Refer to page 37 for the details of model specification items.

## Model/Specifications

Model	Encoder type	Motor (W)	Lead (mm)	Stroke 50mm increments (mm)	Speed (mm/s)	Load capacity (Note 1)		Rated thrust (N)
						Horizontal (kg)	Vertical (kg)	
RCS-RA55-○-100-GD-H-***-△-□	Absolute Incremental	100	16	50~300	1~800	15	2.8	105.8
RCS-RA55-○-100-GD-M-***-△-□			8		1~400	30	8.3	212.7
RCS-RA55-○-100-GD-L-***-△-□			4		1~200	60	17.3	424.3

\* In the above model names, ○ indicates the encoder type, \*\*\* indicates the stroke, △ the cable length, and □ the applicable options.

## Options

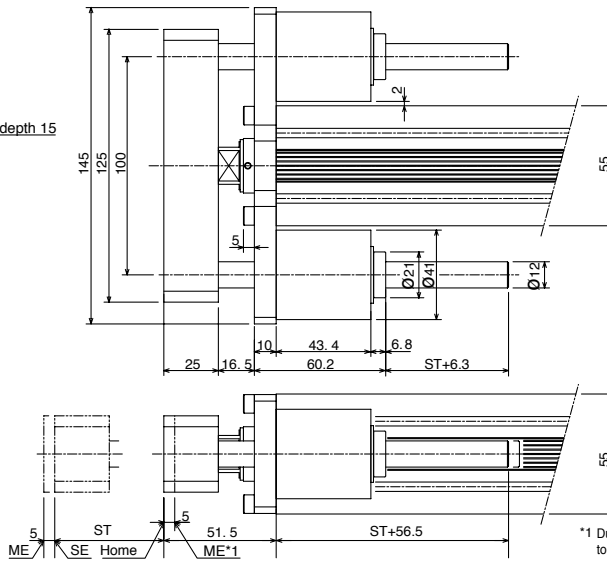
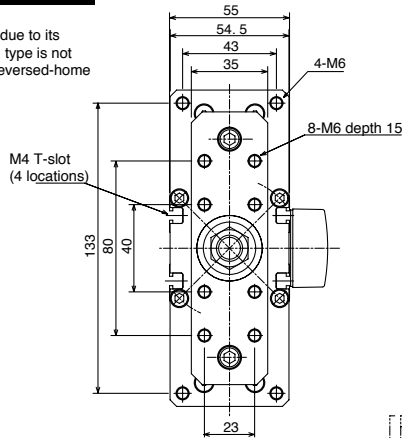
Name	Model	Page
Different connector-cable outlet direction	A2	→P137
Brake	B	→P137
With foot bracket	FT	→P139

## Common Specifications

Drive system	Ball screw Ø12mm, rolled C10
Positioning repeatability	±0.02mm
Backlash	0.05mm or less
Guide	Ball bush guide x 2 (externally attached)
Rod diameter	Ø25mm
Rod non-rotational accuracy	±0.08°
Base	Material: Aluminum with white alumite treatment
Cable length (Note 2)	P: 1m, S: 3m, M: 5m, X□□: Length specification, R□□: Robot cable

## Dimensions

\* Please note that due to its structure, the rod type is not available in the reversed-home specification.



ST: Stroke  
SE: Stroke end  
ME: Mechanical end

\* For the actuator dimensions, refer to the dimensions of the RCS-RA55-100-GN on page 103.

\*1 During home return the slider will move to the ME, so be careful to prevent contact with surrounding parts.

## Dimensions, Weight and Maximum Speed by Stroke

Stroke	50	100	150	200	250	300
Weight (kg)	3.0	3.4	3.8	4.2	4.7	5.1
Maximum speed (mm/s)	H type					
	800					
	M type					
400						
L type						
200						

## Applicable Controller Specifications

Applicable Controller	Maximum number of controlled axes	Compatible encoder type	Program operation	Positioner operation	Pulse-train control	Power supply voltage	Page
RCS-C	1 axis	Absolute/Incremental	X	O	X	AC100/200V	→P163
E-Con	1 axis		X	O	X	AC100/200V	
P-Driver	1 axis	Incremental	X	X	O	AC100/200V	Refer to the separate catalog.
X-SEL	4 axes	Absolute/Incremental	O	△	X	AC100/200V	



(Note 1) A longer stroke will result in a lower maximum speed to prevent the ball screw from reaching a dangerous speed. (Refer to the above table for the maximum speed at a given stroke.)  
 (Note 2) The load capacity is based on operation at an acceleration of 0.3 G (or 0.2 G for the L type). The horizontal load capacity assumes a condition where a guide or guides are used to prevent the rod from receiving radial loads. If no guide is used, refer to the correlation diagrams of allowable tip load and traveling life on page 132.  
 (Note 3) The maximum cable length is 15 m. Specify the desired length in meters (e.g., X08 = 8 m).

\* Refer to page 23 for other points to note.